







ROBOT-COBOT ROBOT AGV

Progea Leonardo srl

progealeonardo.com









	Strong anti-interference ability	Ø
Ether CAT.	High communication frequency and fast speed	⊘
EtherCAT bus	High safety, accurate motion trajectory	⊘
communication	Accessible data for all joints	⊘
8 0	High motion efficiency	⊘
	More possible positions of high difficulty	⊘
Each joint with a	Most flexible collaborative robot	⊘
motion range of ±360°	Low power consumption	⊘
	Self-developed dual-joint modules	⊘
₩	Unique arm design, optimized singularity points	⊘
Self-developed	Higher integration	⊘
dual-joint modules	Higher flexibility	⊘
	Completely self-developed core components from Han's Group	⊘
	Complete set of motors, servo drive	⊘
Self-developed of core	Grating encoder, 6-dimensional force/ torque sensor	⊘
components	Electromagnetic brake, high-speed inverter	⊘
	Support for handheld teach pendant, tablets, computers and other terminals	⊘
Multi-terminal	Graphical programming, intuitive and easy to understand	⊘
Mutti-terriniat	User-friendly interactive design	0





Innovative braking method

The robot will automatically rebound and then stop when encountering any resistance.

Output force and power controlled within the safety range to ensure personnel safety.

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Innovative braking design. The robot will be locked immediately in case of a sudden power failure or emergency stop during operation. It will not slide, fall or move at all

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IP66 protection rating

Higher waterproof and dust-proof protection

Suitable for harsher environments

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Protects against external objects and dust

Applicable to more working conditions

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ISO class 5 cleanroom

The surface cleanliness of the whole robot is excellent due to the excellent waterproof and dust-proof performance

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Optimized structure of internal parts, low mutual friction, avoiding damage

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Excellent sealing of the whole robot, without impurities intrusion

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Automotive and aerospace industry standards, ensuring high quality

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More than 20 years of industrial experience

Incubated from the Robotics Research Institute team of Han's Motor

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More than 20 years experience in motors, servo drives and motion control

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Long-term cooperation with famous universities at home and abroad

Dedicated to collaborative robot technologies and applications

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More open platform

Open source ROS interface, which allows users to control the robot joints in real time through EtherCAT under the ROS environment

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ROS platform, which greatly improves the robot's scalability. The robot can be controlled without an additional control box

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Used for ROS teaching in colleges and universities

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Explosion-proof Certification

Certified by the national instrumentation explosion-proof safety inspection station

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Can be used for special operations in explosive and combustible dust environments

(V)





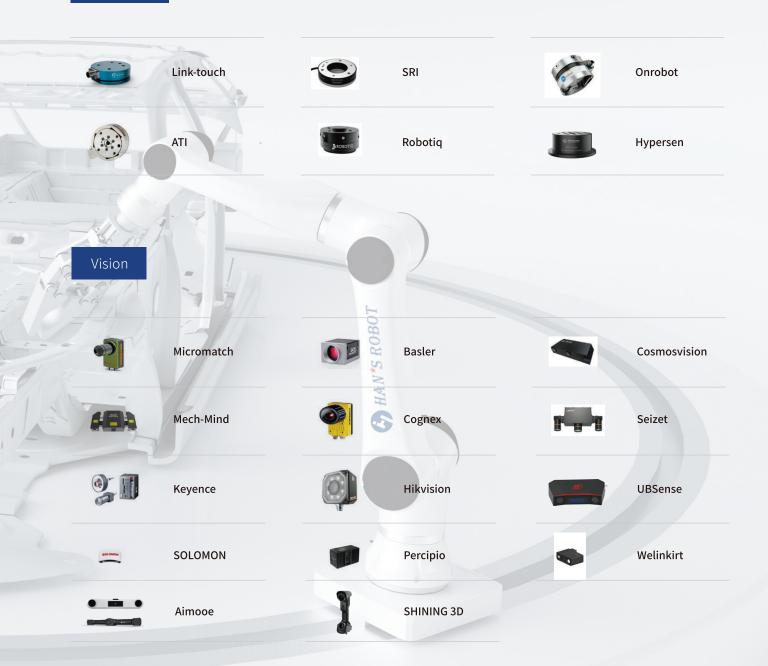
Adhering to the ecological concept of "all are friends in the world", Han's Robot has created a more complete and open collaborative ecosystem, and designed various IO and communication interfaces. These IO interfaces greatly expand the application scope of the robot and can support "plug and play" with most accessories in the industrial ecosystem, such as grippers, vision, and sensors, which can meet the needs of multiple scenarios such as loading and unloading, assembly, testing, handling, screw driving, grinding, spraying etc.

Grippers





Force Sensor





"POSS" Concept

The most reliable body, the smartest brain:

Han's Robot believes that the characteristics of a good collaborative robot can be summarized as POSS. We are dedicated to the research and application expression of cutting-edge robotics technology, and the development of robots with the most reliable body and the smartest brain.











Overview →



Elfin Collaborative Robot

The Elfin collaborative robot can be used in automated integrated production lines, assembly, picking, welding, grinding, spraying and other applications, and has been exported to more than 100 countries and regions. It adopts a unique double-joint module design, where one motion module contains two joints to form a unique kinematic structure, which not only differs from most collaborative robots on the market, but also provides more flexibility when working.



E15 1300mm **15KG**

E03 590mm 3KG









E10-L 1300mm

8KG











Why Elfin

Optimized singularity

The unique arm design not only avoids the product homogeneity, but also reduces the singularity



First dual-joint module design in China

The unique kinematic design enables the robot to have high flexibility. The highly integrated modular design minimizes the arm weight



Highly flexible 6-DOF collaborative robot

The collaborative robot with 4/6-axis coaxial structure has almost reached the flexibility of 7-DOF robots





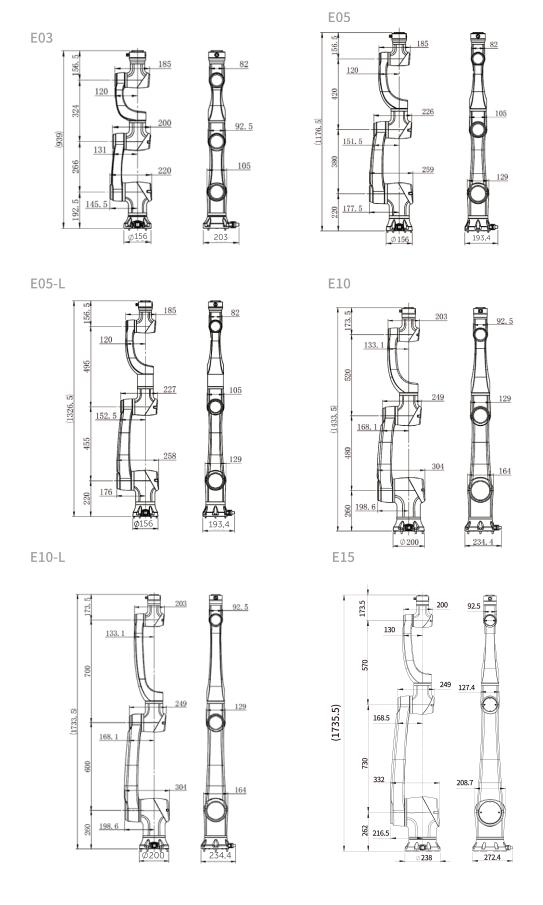
Technical Specifications



Model	E03	E05	E05-L	E10	E10-L	E15	
Weight	18kg	25kg	26kg	43kg	45kg	60kg	
Payload	3kg	5kg	3.5kg	10kg	8kg	15kg	
Reach	590mm	800mm	950mm	1000mm	1300mm	1300mm	
Power Consumption	100W typical application	180W typical application	180W typical application	350W typical application	350W typical application	600W typical applicatio	
Joint Range			±3	60°			
Joint Speed	J1-J4 180°/s J5-J6 200°/s	J1-J4 180°/s J5-J6 200°/s	J1-J4 180°/s J5-J6 200°/s	J1-J2 100°/s J3-J4 150°/s J5-J6 180°/s	J1-J2 100°/s J3-J4 150°/s J5-J6 180°/s	J1-J2 80°/s J3-J4 120°/s J5-J6 150°/s	
Tool Speed			2n	n/s			
Repeatability	±0.02mm	±0.02mm	±0.02mm	±0.03mm	±0.03mm	±0.05mm	
Degree Of Freedom			(ô			
End I/O Port		Digit	al input: 3, digital o	utput: 3, analog inp	out: 2		
Control box I/O port		Digital input: 1	6, digital output: 16	i, analog input: 2, a	nalog output: 2		
I/O Source		24V 2A					
Communication	TCP/IP,ModbusTCP,Profinet (Optional),Ethernet/IP (Optional)						
Programming	Graphical programming, remote call interface						
IP Classification	IP54						
Collaborative Operatio	on 10 advanced security configuration functions						
Main Material	Aluminum alloy						
Working Temperature	0-50°C						
Power input	200-240V AC, 50-60Hz						
Cable	Cable to the control box: 5m; cable to the teach pendant: 5m						







Elfin-Pro Collaborative Robot

Elfin-PRO collaborative robot is developed on the basis of elfin collaborative robot. It not only has all the advantages of the elfin collaborative robot such as a variety models, easy deployment, high precision, high flexibility, double-joint module design and modular design, but also has upgraded the product capability through the integration of cutting-edge AI technology, end force control integration, end vision integration. In addition, it adopts a new elegant and practical surface treatment process which is more stable and reliable. With all these advantages, Elfin PRO offers a better human-robot collaboration experience and could support wider application scenarios.



E03-Pro 590mm 3KG



E05-Pro 800mm 5KG



E05L-Pro 950mm 3.5KG



E10-Pro 1000mm **10KG**



E10L-Pro 1300mm 8KG



Why Elfin-Pro

Force Control Integration

- a.Internal wiring with better anti-interference ability
- **b.**Constant force control for perfect trajectory
- c.Fast programming
- **d.**Soft control with smooth free-drive teaching
- e.Force exploration suitable to intelligent assembly which makes the small batches and flexible production of multiple varieties to be possible.



Camera System

- a.Internal wiring enables the robot to have better anti-interference ability and supports fast deployment
- **b.** Al application capabilities such as visual positioning, visual classification recognition, object detection and QR Code recognition
- c. Han's Robot's self-developed hardware and software which is easy to operate and pretty interactive and scalable.



Higher Protection, more applications

With IP66 protection, E PRO robot can be adapted to different production environments which further extending the range of applications.







	Model	E03-Pro	E05-Pro	E05L-Pro	E10-Pro	E10L-Pro		
	Weight	18kg	25kg	26kg	43kg	45kg		
	Payload	3kg	5kg	3.5kg	10kg	8kg		
	Reach	590mm	800mm	950mm	1000mm	1300mm		
	Control Box Dim	ension	5	36*445*319mm				
	Joint Range			±360°				
	Joint Speed	J1-J4 180°/S J5-J6 200°/S	J1-J4 180°/S J5-J6 200°/S	J1-J4 180°/S J5-J6 200°/S	J1-J2 100°/S J3-J4 150°/S J5-J6 180°/S	J1-J2 100°/S J3-J4 150°/S J5-J6 180°/S		
	Tool Speed			2m/s				
Robotic Arm	Repeatability	±0.02mm	±0.02mm	±0.02mm	±0.03mm	±0.03mm		
Parameters _	Degree of freedo	om		6				
	End I/O port		Digital input: 3, o	digital output: 3, a	nalog input:2			
	Control box I/O	port Digital	input: 16, digital outpu	ut: 16, analogue in	put: 2, analogue outp	out: 2		
	I/O Source			24V 2A				
	Communication	TCP/IP, Mod	busTCP, Profinet(exter	nal conversion), E	thernet/IP (external c	onversion		
	Programming		Graphical progra	mming, remote ca	alling interface			
	IP Classification			IP54				
	Collaborative Op	peration	10 advanced se	ecurity configurati	on functions			
	Main Material		Į.	Aluminium alloy				
	Working Temperature 0-50°C							
	Power input		200-240V AC, 50-60Hz					
	Cable	Cable Cable to control box: 5m, cable to teach pendant: 5m						
	Communication	frequency		1kHz				
Force	e control parameter	s (optional)	Vis	ion parameters (o	ptional)	Protection (optiona		
Force	control, tool flange F	Force x-y-z、Torque x-y-z	Al functions	Image class	ification, object detection	n Class IP66		
Range	4	200N, 10Nm	Application	Positioning				
Precisi	ion 2	2N, 0.1Nm	Positioning accurac	2D, 0.2mm				
Accura	acy 4	1N, 0.2Nm	Camera	5 megapixel	s, working distance 100n	 nm~∞		
			External vision (opt	ional) Laser senso	r or a depth RGBD camer	 ra		
	G consists			,				
	/					9		
				OPER.				
Control Box			Mini Control Box (Optiona	1)	Teach Per	ndant		
Dimensions	445.2mm x 318	.8mm x (360+176)mm	Dimensions	323x221x80(mm)	Dimension	ns 327 mm x 230 mm x (45+22) r		
Stand Height		176mm	Power Input	DC30~60V	Weight	2.7kg (Include Cable)		
Weight		18.5kg	I/O Source	DC24V	Display —	10.4"		
Power Output		48V DC	I/O Port	Inputs 8 , Outputs	8 Resolution	n 1024 x 800		
Working Temp	erature	0~50°C	IP Classification	IP20	E-stop Bu	tton 1		

IP Classification

Working Humidity 90% Relative Humidity (non-condensing)

IP20

Communication

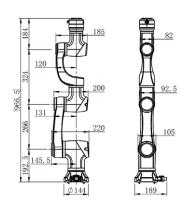
TCP/IP Modbus

IP Classification

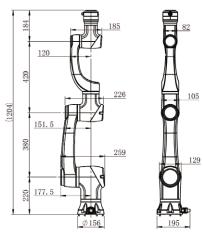
IP54



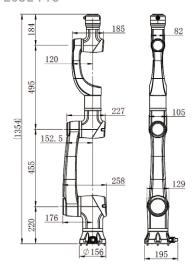
E03-Pro



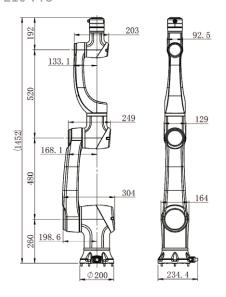
E05-Pro



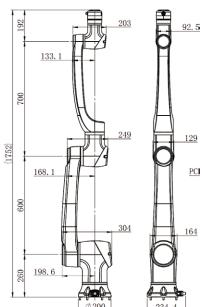
E05L-Pro



E10-Pro



E10L-Pro



S Collaborative Robot

Han's Robot S series collaborative robot with high payloads and long arm reach, which can easily handle a super heavy 20KG payload and 1300mm~1700mm working radius. It can be widely used in machine loading and unloading, palletizing, assembly and heavy load handling applications. Han's Robot S series collaborative robot is a great tool for users to improve their productivity comprehensively, with a qualitative leap in product performance, safety protection, response time and anti-interference capability.

Why S

Suitable for heavy load scenarios

With a rated load of 15kg~20kg and a maximum working radius of 1700mm, it can cover a wide range of complex and large load applications



Security collaboration

Based on core independent research and development capabilities, it has 10 advanced safety configuration functions such as collision detection, making human-machine collaboration more secure and reliable



Extremely fast response

End-to-end EtherCAT bus communication, compatible with high power supply and Gigabit Ethernet, real time control refresh frequency of 1000/5000 Hz and industry leading control accuracy



Very low barrier to entry

Support pad, computer, instructor and other multi-terminal graphical control, 30 minutes to learn to change the programming methods, 1 hour to start operation



Simple customisation and easy deployment

The modular design of the whole machine, from the module to the boom, can meet the individual needs of customers, easy to install and dismantle, to achieve flexible deployment and easy maintenance



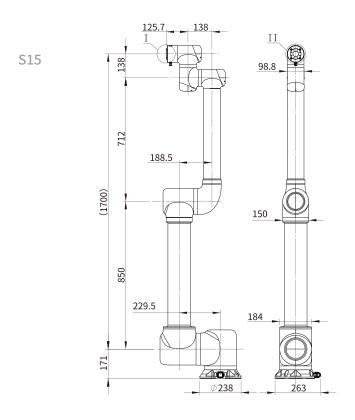


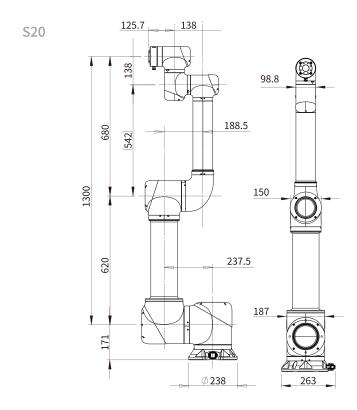


Model	S15	S20			
Weight	64kg	63kg			
Payload	15kg	20kg			
Reach	1700mm	1300mm			
Power consumption	800W typical application	800W typical application			
Joint Range	±360°	±360°			
	J1-J2 90°/s	J1-J2 90°/s			
Joint Speed	J3-120°/s	J3-J4 120°/s			
	J4-J6 180°/s	J5-J6 180°/s			
Tool Speed	1.8m/s	1.6m/s			
Repeatability	±0.1mm	±0.1mm			
Degree of freedom		ô			
Control b o x dimension	536*445	*319mm			
End I/O port	Digital input: 3, digital ou	tput: 3, analogue input: 2			
Control box I/O port	Digital input: 16, digital output: 16, a	nalogue input: 2, analogue output: 2			
I/O Source	24\	/ 2A			
Communication	TCP/IP an	d Modbus			
Programming	Graphical programming	g, remote callinterface			
IP Classification	IP	54			
Collaborative operation	10 advanced security o	onfigunation functions			
Main material	Alumini	um alloy			
Working Temperature	0-5	0°C			
Working remperature	200-240V AC, 50-60Hz				
Power input	200-240V A	AC, 50-60Hz			









Elfin-Ex Explosion-proof Collaborative Robot

Overview

Han's Robot introduces the explosion-proof collaborative robots, which have received national certification for explosion protection. It can replace workers and work in explosive hazardous environments to significantly reduce operational risks.

The series adopts a leak-compensated positive pressure explosion-proof system with medium isolation of the ignition source, and the shell is designed with multiple sealing structures, thus realising a compound explosion-proof structure of intrinsic safety and positive pressure; equipped with a positive pressure monitoring system, the positive pressure protection gas pressure of the robot can be monitored in real time and provides power failure protection, blocking explosive combustible gases and dust from entering the robot to avoid the risk of explosion.

E05F 800mm 5KG

E10F 1000mm 10KG



E10F-L 1300mm 8KG



E15F 1300mm **15KG**





Basic Configuration



Positive pressure explosion-proof robots -proof demonstrator

Built-in pressure sensor, positive pressure explosion -proof construction



Intrinsically safe and explosion Positive pressure explosion-proof

Intrinsically safe and explosion-proof



Electric Control Cabinet

Robotic arm control module, explosion-proof cabinet with pressure monitoring system to ensure normal ope ration of the arm in real time and protection against po wer failure in case of pressure abnormalities





Say "no" to explosions with multiple blast protection

A leak-compensated positive-pressure explosion-proof system with medium isolation of the ignition source is used for reliable sealing performance; the shell is sealed with multiple seals, thus realising an intrinsically safe, positive-pressure and other composite explosion-proof structure; equipped with an air pressure monitoring system for full process detection, reducing the risk of explosion to zero.

Reliable sealing against water and dust ingress

The robot is designed with a reliable and highly hermetic structure to achieve IP66 level of protection against water and dust.

Easy to use, flexible and convenient

No professional knowledge of explosion-proofing and programming is required, even if you have no basic knowledge you can easily get started; fast drag-and-drop operation, automatic programming, high intelligence

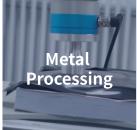






Мос	del	STAR-S	STAR-L	STAR-M	STAR-H			
Main	Vehicles	HR150	HR300	HR600	HR1200			
body	Robot	E03/E05	E03/E05/E05-L/E10	E05-L/E10/E10-L/E15	E05-L/E10/E10-L/E15			
	Dimensions (Elfin Not Included)	700*500*630(mm)	950*650*900(mm)	1200*700*900(mm)	1530*965*1300(mm)			
Basic performance	Actuation	Differential Drive	Differential Drive	Steering Wheel	Differential Drive			
	Tray Lifting Unit		Customizable	e				
Running	MAX Velocity	1.5m/s	1.5m/s	1.1m/s	1.5m/s			
performance -	Navigation Mode Laser SLAM, Hybrid Navigation (Fusion Vision) (Optional)							
Vision	Vision (Standard Mode) Camera (Customizable)							
performance	Positioning Accuracy		±0.5mm					
Software	Operating Software Han's Robot application software / Dispatching software (optional)							
Software	Development Platform		Windows/Linu	ıx				
	Battery Voltage		DC 48V					
Endurance performance	Running Time (with load)	>6h	>10h	>12h	>12h			
	Charging Time	≤2 hours	≤2 hours	≤2 hours	Manual Charging≤2.5 hours			
External Interface	Standard Communication Ir	iterface	TCP/IP, HTTP, S	DK				
	Outbound Interface		12 Months					





















↑ Industry applications:

Han's Robot collaborative robots have been widely used in electronics, automotives, semiconductors, metal processing, new energy, pipeline inspection and other fields. Han's Robot uses robot technologies for collaboration in global intelligent manufacturing, which promotes productivity in all walks of life.

↓ Process applications:

Loading and unloading, welding, marking, assembling, polishing, handling, inspecting, gluing, picking, screwing, etc.





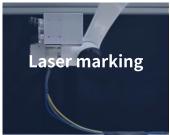












Mini electrical box customised explosion-proof robot

E, E, E, E, ci ci ci ci

Explosion-proof robot arm body

Built-in pressure sensor, positive pressure explosion-proof construction



Mini electric control box

Wireless router and audible and visual alarms, with wireless ipad operation, body pressure monitoring and power failure protection in abnormal conditions



Explosion-proof iPad

Intrinsically safe explosion-proof



Explosion-proof robot arm body

Built-in pressure sensor, positive



Mini electric control box

Wireless router and audible and visual alarms, with wireless ipad operation, body pressure monitoring and power failure protection in abnormal conditions



Non-explosion-proof iPad /laptop

Wireless connection, no explosion protection, to be used

Customised explosion-proof robot with standard electric control box



Explosion-proof robot arm body

Built-in pressure sensor, positive



Standard electric control box

Wireless router and audible and visual alarms, with wireless ipad operation, body pressure monitoring and power failure protection in abnormal conditions



Explosion-proof iPad

Intrinsically safe explosion-proof



Explosion-proof robot arm body

Built-in pressure sensor, positive pressure explosion-proof construction



Standard electric control box

Wireless router and audible and visual alarms, with wireless ipad operation, body pressure monitoring and power failure



Non-explosion-proof teach pendant

Wired connection, not explosion-proof, to be environments

Explosion-proof control cabinet version of the explosion-proof robot



Explosion-proof robot arm body

Built-in pressure sensor, positive



Explosion-proof control cabinet

Robotic arm control module, explosion-proof cabinet with pressure monitoring system to ensure normal operation of the arm in real time and protection against power failure in case of pressure abnormalities



Explosion-proof iPad

Intrinsically safe explosion-proof



Explosion-proof robot arm body

Built-in pressure sensor, positive pressure explosion-proof construction



Explosion-proof control cabinet

Robotic arm control module, explosion-proof cabinet with ensure normal operation of the arm in real time and protection against power failure in case of pressure abnormalities

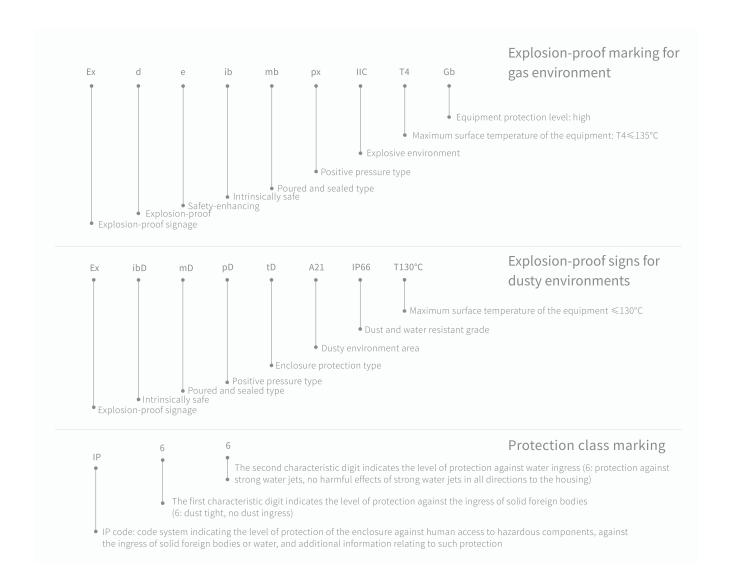


Non-explosion-proof iPad /laptop

Wireless connection, no explosion protection, to be used (optional on request)

- Certified by the national instrumentation explosion- proof safety inspection station
- 2 Complies with GB3836/GB12476 national standards
- 3 Meets the requirements for normal operation in Zone 1 and Zone 2 explosive gas environments and Zone 21 and Zone 22 explosive dust environments
- 4 Can be used for special operations in explosive and combustible dust environments



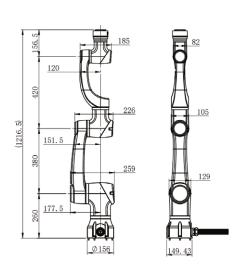


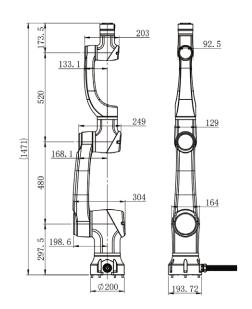


Model	E05F	E10F	E10F-L	E15F		
Weight	25kg	43kg	45kg	60kg		
Payload	5kg	10kg	8kg	15kg		
Reach	800mm	1000mm	1300mm	1300mm		
Joint Range		J1-J6	±360°			
Joint Speed	J1-J4: 180°/s J5-J6: 200°/s	J1-J2: 100°/s J3-J4: 150°/s J5-J6: 180°/s	J1-J2: 100°/s J3-J4: 150°/s J5-J6: 180°/s	J1-J2: 80°/s J3-J4: 120°/s J5-J6: 150°/s		
Maximum tool speed		2n	n/s			
Repeatablity	±0.02mm	±0.03mm	±0.03mm	±0.05mm		
Explosion-proof IP Classifi	cation	Ex d e ib mb px IIC T4 Gb Ex ibD mD pD tD A21 IP66 T130°C				
Degree of freedom	6					
Control box I/O port	Digital input: 16, digital output: 16, analogue input: 2, analogue output: 2					
Communication	TCP/IP, ModbusTCP, Profine(t O p tional), Ethernet/IP(Optional)					
Programming	Graphical programming, remote call interface					
IP Classification	IP66					
Collaborative operation	10 advanced security configuration functions					
Main material	Aluminium alloy					
Working Temperature	-20—40°C					
Power input	200-240V AC, 50-60Hz					
Cable	Maximum length customizable 15-20m					

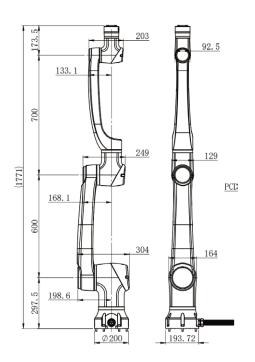


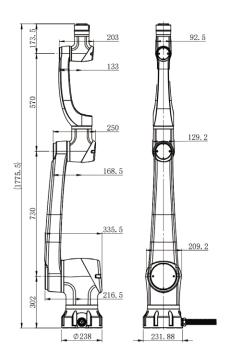
E10F E05F





E10F-L E15F







HR Multi-sensing Autonomous Vehicle

Overview

HR is a new generation of multi-sensing autonomous vehicles from Han's Robot, used for indoor intralogistics tasks. It can autonomously transport items and navigate freely in its environment. As a mobile robot, it makes the labor of the workers easier and improves business efficiency. This robot is also equipped with obstacle avoidance radar, which can work continuously and safely without interruption. Moreover, it has built-in autonomous navigation system and dispatching software, which enable multiple HR to serve simultaneously, keep the production running and maintain the flexibility of its manipulation.



Dimensions

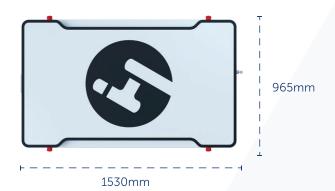
HR-150 150kg **30AH**





HR-1200 1200kg 125AH









Payload 150kg / 1200 kg



High speed charging and long endurance



HR Speed 1.5 m/s



3D Visual Sensor (optional)



Artificial Intelligence

Path Optimization, Smart Interaction



Safe Human Detection

Touchless Sensor Technology



Status Visualization

LED lights can show the robot'sworking status

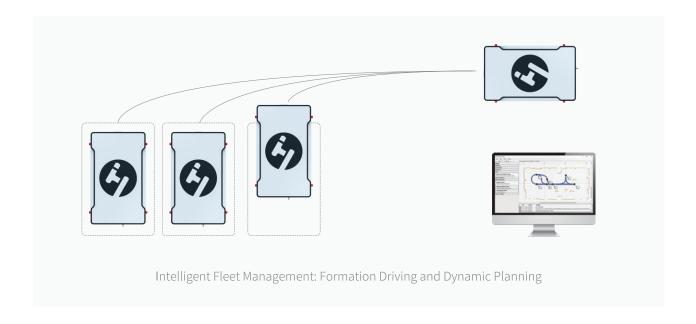






HR+Elfin

HR for Logistics



Recommended Industries







Healthcare

Logistics

3C



	Model	HR-150	HR-300	HR-600	HR-1200
	Payload	150 kg	300kg	600kg	1200kg
	Dimensions	700*500*255(mm)	950*650*350(mm)	1200*700*280(mm)	1530*965*295(mm)
Basic parameters	Navigation Mode Laser SLAM, Hybrid Navigation (Fusion Vision) (Optional)				
	Actuation	Differential Drive	Differential Drive	Steering Wheel	Differential Drive
	MAX Velocity	1.5m/s	1.5m/s	1.1m/s	1.5m/s
	Positioning Accuracy ±10mm				
	Communication Interface TCP/IP, Modbus TCP				
	Outbound Interface WiFi, 1XRJ45, 5G Internet				
	Lifting Units (Optiona	l) Customizable 1	.X200Kg,1X0-60mm(include	ed) Customizable	4X400Kg,4X0-50mm (included
	Battery Voltage DC 48V				
	Battery Capacity	30AH	67AH	72AH	125AH
Battery parameters	Charging Time	≤2 hours	≤2 hours	≤2 hours	Manual Charging≤2.5 hours
	Charging Mode	Automated / Manual	Automated / Manual	Automated / Manual	Manual / Wireless
	Running Time (no loa	d) >6h	10h	12h	12h
Software	Operating Software	Han's F	Robot application software	/ Dispatching software	(optional)
Others	Warranty		12 Mo	onths	



STAR Mobile Manipulator

Overview

The STAR mobile manipulator is an intelligent mobile robot, which combines the self-developed mechanical arm and mobile robot, vision system, gripper and other components to perform mobile operations to achieve functional applications such as grasping, handling, assembly, and detection of materials. According to the customer's on-site use environment, it can match the corresponding scheduling system for flexible scheduling and rapid deployment. The core units of the STAR are independently developed, with high cost performance and strong system scalability, which can connect to the customer's MES (or other systems) and provide rich solutions according to different needs of customers. It can serve the future intelligent manufacturing industry 4.0.

It is mainly used in industries (such as electronics, metal products, auto parts, electricity, new energy, ships, aerospace), healthcare, family services, file management and other applications.



Features



Rapid Deployment

Based on the SLAM navigation technology, without the scene transformation, the environment map is automatically generated, the scheduling planning service is realized, and the deployment is fast.



Self-check

It can obtain the robot hardware and operating status in real time, which realizes self-check and fast fault diagnosis.



Automatic charging

The STAR can automatically go back to charging pile for recharging, which ensures the robot to achieve 7*24 all-day operation and high-frequency fast response between tasks.



Intelligent scheduling

Based on the self-developed architecture and intelligent planning algorithm, the large-scale scheduling of robots is realized to ensure the efficient operation of the system.



Stable performance

With independent development of core components, it shows the perfect combination of body and arm, and the performance is more stable.



Strong Scalability

It efficiently connects to the enterprise's MES/WMS information system and can quickly install application function modules according to requirements.



Automatic lifting

The internal materials are automatically lifting, which can maximize the use of body space, store more materials in a limited space, and reduce material transfer.

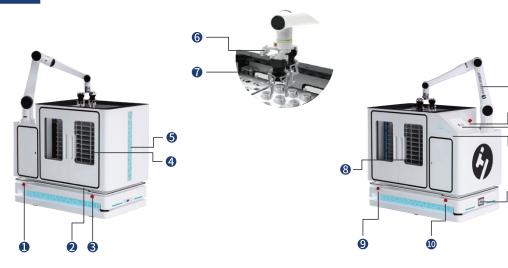




Intelligent obstacle avoidance

Equipped with sensors such as lidar and visual camera (optional), it can intelligently identify obstacles, actively park and avoid obstacles.

Parts name



E-STOP

0000

Drainage Outlet

Lifting Unit 1 4 (To Be Processed)

Singal Lights 6 4

3D Camera

Electric Gripper

Lifting Unit 2 (Finished Product)

E10-L (Optional)

12" Touchscreen

B

8 ❶

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Electronics manufacturing industry

Laser cutting

One robot is used for loading and unloading for four laser cutting machines at the same time. The four cutting machines are placed in pairs, and a 7-axis guide rail is used in the middle to realize the motion of the collaborative robot between the machines. A vision camera is integrated to the robot to realize the positioning for loading and unloading as the required unloading precision of the laser cutting machine is about 0.1 mm.

Space-Saving

Easy to operate

The overall layout is compact which occupies a small area, and there is no need to do great changes to the original plant. Moreover,the equipment deployment is easy.

It is easy to operate the collaborative robots. Customers can switch products or debug new products by themselves after simple training, which greatly reduces the cost of product replacement.



More scenarios: loading and unloading, inspecting, grinding, spraying, assembling, marking, etc.

Automotive manufacturing industry

Gluing for car lights

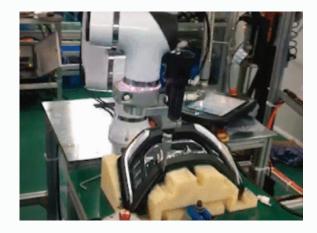
By adopting one-to-two structure integration, one cold glue device supplies can glue for two collaborative robots. The double-station free gluing improves the gluing efficiency and quality and avoids the impact on the personnel health, which greatly reduces labor and equipment costs.

Safe and flexible

Energy saving and low consumption

High-precision linear gluing, improved yield rate.

The cold glue does not require heating, which greatly reduces energy consumption.



More scenarios: loading and unloading, spraying, assembling, inspecting, picking, marking, etc.



Healthcare industry

Medical Surgical Robot

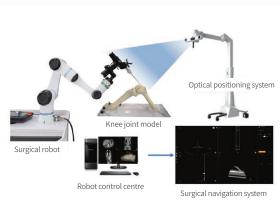
The orthopaedic drilling and stapling robot, in conjunction with the optical positioning system and other equipment, achieves a more intelligent and reliable surgical plan, a more precise and humane surgical execution, and an improved level of service in orthopaedic drilling and stapling surgery.

Accuracy: The robot can be positioned with an accuracy of up to 0.02mm, enabling precise reproduction of the position and force of the billion dollar operation, ensuring precise and accurate surgery.

Safety: The safety of human-machine collaboration is ensured through advanced safety functions such as collision protection, motion area restriction and check pressure protection; at the same time, surgical safety is guaranteed based on the advantages of high precision and high sensitivity.

Humanisation: Soft movement control and real-time pressure tracking control for expert-like results and reduced patient stress.

Efficiency: The robot is stable, safe and easy to use and can perform continuous surgery.



More scenarios: puncture, dental implant, neurosurgery, abdominal puncture, hip replacement surgery, etc.

Hybrid robot

CNC loading and unloading

In this case, the mobile manipulator moves intelligently in the same workshop to support multipleproduction

CNC production workshop material transfer project Automatic loading and unloading items of materials.

Case features

Han's robot 6-axis collaborative robot + intelligent mobile robot, with its large capacity and automatic lifting mechanism, can load more materials at one time, freely shuttle in the workshop, ensure the normal operation of multiple equipment in the workshop, and help customers to automate production needs.

More scenarios: warehousing, packaging, assembling, testing, pickup, etc.





Metal processing industry

Laser Marking

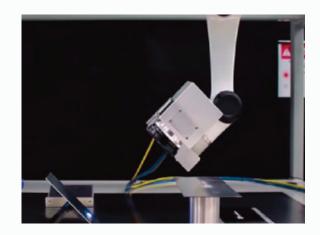
Han's marking robots can realize multi-directional automatic marking, from loading and unloading to marking, which meets the unmanned, automated, and flexible use requirements, improves the delivery efficiency, and reduces production costs.

Flexible and efficient

Easy to operate

Realize flexible, efficient, multi-angle, multi-material free marking.

Graphical programming and robot program editing are simple and easy.



More scenarios: marking, rust removal, grinding, screwing, welding, etc.

Semiconductor **Industry**

Wafer handling

Han's hybrid robots interwork with wafer processing equipment to provide MES whole-factory automated wafer handling solutions, and fully independent IPR upper-computer scheduling system and planning.

Fast and robust

One robot is connected to five wafer processing devices for loading and unloading, and the efficiency is 68% higher than manual operation. The fully automated black light factory works automatically in a controllable manner. Multiple devices can be independently scheduled in 24-hour operation.



More scenarios: lithography, cleaning, etching, precipitation, equipment care, grinding, etc.



Sanitary industry

Spin welding

Solve the pain points of ultrasonic welding with high noise and inconsistent manual feeding pace. Less labor and higher efficiency, easy to operate, stable robot production.



More scenarios: visual grasping, gate polishing, assembling, picking and placing, hot plate welding, loading and unloading, etc.

Pipeline inspection industry

Pipeline equipment inspection

In this application, Han's Robot is integrated with various sensors to realize 24-hour visual automatic inspection in the pipeline. The 6-DOF joint design allows the robot to be better planned for complex motion paths, increases the monitoring scope and precision, and achieves no-blind-angle monitoring.

Diverse applications

Less risks

Used in power, energy, petroleum, transportation, smart buildings, etc.

Less safety risks and labor costs compared with traditional manual inspections



More scenarios: electricity, energy, construction, transportation, minerals, marine.



Education industry

VR training

1. VR industrial robot task training system based on virtual reality. It realizes multi-brand, multi-robot, multi-scene robot task operation training, including robot welding training, robot spraying training, robot casting training, robot palletizing training, robot loading and unloading training, and robot mobile phone assembly training. 2. Learn and master the operations of industrial robots through the VR robot system, and practical training of physical collaborative robots, which further deepens and consolidates the basic knowledge and skill training results of industrial robots, and greatly improves the teaching and training effects.



More scenarios: teaching platform, cyclic assembly line, mobile robot application, SCARA application, laser marking robot loading and unloading workstation, disassembly and installation of collaborative robot, robot integrated standard workstation.

New retail industry

Milk tea robot

In this application, a new tea flagship store uses Han's robots in the beverage production area to collaborate in tea making, blending, and delivery, which adds value (such as freshness, attractiveness, and customer experience) to its service and image and greatly speeds up beverage production.

Fresh experience

Save kitchen labor

One-click self-service, widely used in airports, hotels, restaurants, stations, shopping malls, and other places

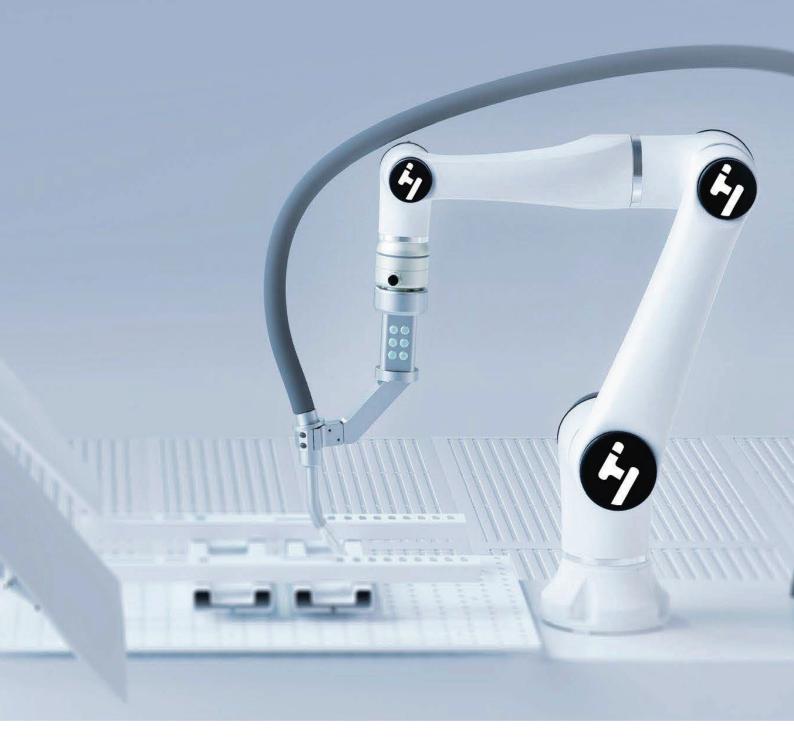
Less labor and higher efficiency, easy operation, convenient maintenance, short time period of cost recovery

More scenarios: massage, coffee latte, unmanned sales, etc.





Automated Welding Workstation (Gas Shielded Arc Welding) Application Solution





Traditional Welding Pain Point



Difficult Programming, High Requirements

Programming for traditional welding robots is difficult to get right in one step and requires continuous debugging and program modification, demanding high programming skills from operators.



Difficult to Hire, Low Efficiency

It is challenging to train and hire skilled welders. Coupled with the highly repetitive rhythm of operations, the efficiency of manual welding is not high.



Unstable Welding Quality

During manual welding, factors such as welding speed and wire feed length vary from person to person, making it difficult to guarantee product quality stability and consistency.



Heavy Workload and Poor Working, **Conditions for Welders**

The welding operation site has high temperatures, and manual welding has safety risks such as burns and arc burns, posing challenges to corporate safety production.







Hans Robot's automated welding workstation (gas shielded arc welding) is composed of the Elfin-Pro series collaborative robot, welding torch, welding system, etc. The Elfin-Pro series collaborative robot has advantages such as integrated end force control, integrated AI vision, and high repeat positioning accuracy. In conjunction with the laser vision seam tracking system, it realizes flexible dragging, automatic tracking, automatic correction, and supports long-time, uninterrupted, high-quality, and highly stable welding work. It primarily enhances cost-effectiveness in automated production fields such as auto parts, engineering machinery, and metal processing.

Equipment Composition





With integrated end force control and Al vision, the system offers simple and efficient control, saving time and effort, thereby improving production efficiency.



Compatible with mainstream welder, it supports free switching between pulse and DC welding, ensuring good stability.



Welding Software Package

Independently developed by Hans Robot, our software uses a graphical interface that is clear and easy to use.



Featured Applications

Drag-and-Drop Teaching, Laser Vision Seam Tracking, Arc Tracking, Welding Plugin

• Drag-and-Drop Teaching:

Simple operations can achieve linear or circular welding

Elfin-Pro supports integrated end force control, allowing users to drag the welding torch easily and quickly to the designated target welding point. With the end button, they can quickly establish a welding task, complete circular/linear path selection, and set up arc starting/stopping. One drag and drop can be reused.







Progea Leonardo srl ⋈ info@progealeonardo.com ⊕ progealeonardo.com

2 Laser Vision Seam Tracking:

Real-time correction of welding deviation to achieve automatic seam tracking

With the laser vision seam tracking system, welding deviations are corrected in real time, ensuring that the welding gun always stays at the center of the seam during movement. This allows for automatic seam tracking, thus improving welding quality.

3 Arc Tracking:

An arc tracker can collaborate with the robot to obtain the relative position of the welding gun and the groove by collecting and processing arc signals, correcting any deviations in the robot's planned path.

Easy-to-Use Welding Plugin:

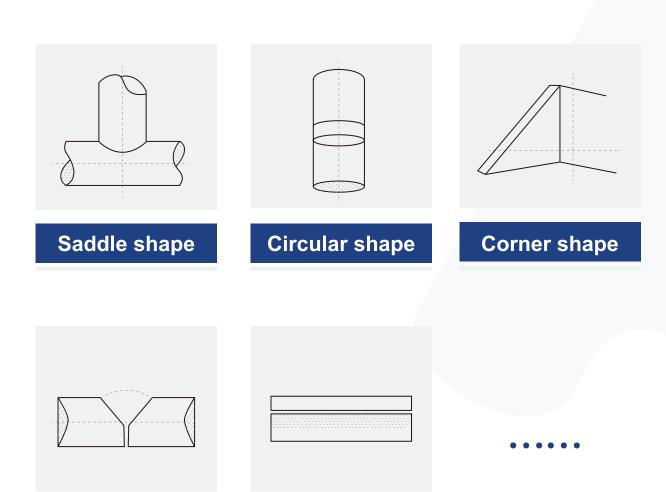
Hans Robot provides an easy-to-install, easy-to-use welding plugin. The user-friendly interface meets visual and graphical operation needs, enables benign human-machine interaction, and improves production efficiency.





Line shape Meet various welding scenarios

The workstation supports arbitrary welding trajectories, splice trajectories, and caters to saddle shape, round shape, corner shape, V-shape, and various other welding modes, covering a vast majority of welding application scenarios.



V-shape

Line shape

Simpler operation procedures

The Han's Robot automated welding workstation (gas shielded arc welding) can rapidly operate through point setting, drag teaching, and intelligent remote sensing. The welding technique package can flexibly configure current, voltage, welding speed, welding posture, etc., meeting users' needs for quickly setting up various welding applications.

Step 1.

1. New creation of welding

2. Setting of the start point of the welding track.



Step 2.

Setting of the starting arc welding parameters: welding time and welding current.



Step 3.

Setting of the end point of the welding track.



Step 4 ·

Setting of the end-arc welding parameters: Arc crater time, burn back time, dwell gas feed time and current.



Step 5.

Operation of welding task.





Main Configuration

Con	nfiguration One (★Recommend	ded) Configuration Two	Brand
Robotic System	 Elfin Pro Welding Robot Body (E10-Pro, E10L-Pro) Controller and Control Cable Teaching Device and Flexible Cable 	Elfin Welding Robot Body (E10, E10-L, E15) Controller and Control Cable Teaching Device and Flexible Cable	Han's Robot
Force Control System	/	Robot Force Control + Control Handle	Force Control
Welding System	 Full Digital Industrial Welding Power Supply Welding Cable, Control Cable and Other Accessories Wire Feeder Protective Gas Detection Switch, Flowmeter, Air Pipe, Protective Gas Cylinder, etc. 		MegMeet, Aotai, Miller, Lincoln, Binzel, Fronius, EWM, Lorch, Esab, Kemppi, Panasonic, OTC DAIHEN
Welding torch system	① Robot Welding Torch ② Welding Torch Holder		Kunshan Rihao, Binzel, Other Brands
System Software	Arc Welding Software Package		Han's Robot
Mobile Workstation	Pillar + Base		Han's Robot
Optional Accessories	Intelligent Remote Sensing		Han's Robot
Unit	S	Set	
Quantity		1	

Performance Indicators

Per	formance Indicators of Automated Welding Workstation
Floor Space	2m×1.5m
Work Cycle	7×24h
Welding Power Supply	MegMeet, Binzel, Aotai
Operator Requirements	Ordinary Staff





Multiple control techniques for high-quality welding

Short-circuit transition control process with special energy control, "pulse energy regulation" of the melt-drop transition control process, and the synergistic process based on variable wire feed speed pulsed energy control process, which is extremely suitable for the consistent high quality welding of carbon steel, stainless steel, aluminum alloys, etc. uniformly high quality welding.



Graphical programming, quick mastery within 10 minutes

The welding process package integrates a wealth of parameters to meet the needs of the welding process. Straight or circular welding can be carried out with simple commands:select and define linear,circular,zigzag paths by moving the robot arm to the points of your choice and locking them with buttons on the flange to make welding as easy as using a mobile phone.



Flexible drag teaching, improved work efficiency

The Elfin-Pro series collaborative robot integrates end force control, possesses excellent precision and accuracy, realizes smoother, more efficient drag teaching abilities. A one-time teaching for repeated use can automate and continually perform welding tasks, significantly improving work efficiency.



Multiple safety protections ensure safe production

Han's Robot uses an electromagnetic brake mode in the event of a sudden power failure or emergency stop during operation, it can be held directly without falling, which effectively increases operational safety.



User-friendly UI interface, for stress-free work

Han's Robot optimizes and upgrades the system UI interface based on actual user application scenarios, allowing the robot to serve users better.

















Industry Applications

Metal Working

Metal forming is often associated with high levels of labor, noise pollution and metal dust. Sometimes in hot, humid and even polluted environments, the work is simple and boring, making it difficult for companies to recruit staff. The application of collaborative robots can not only solve the problem of employing people in enterprises, but also improve processing efficiency and safety in order to enhance processing accuracy. This solution has great scope for application.





Automobile Components

In recent years, the automotive industry has diversified in order to meet the needs of the general public Traditional welding cannot meet the segmented and multiscene welding needs of automotive component manufacturing. Han's Robot's welding equipment allows for flexible layout and production. It collaborates with people in modern automotive parts production plants in order to increase production efficiency.

Shipbuilding

There are nearly a thousand welded components in the ship's structure and nearly ten thousand parts involved. Many of the important load-bearing components of the ship are welded components, and the ship's hull is subjected to significant pressure during operation. This is reason of the welding requirements are so stringent. Han's Robot has a repeatable positioning accuracy of down to ± 0.02 mm, which enables precise welding of the ship's components in automated welding processes.





Kitchen and Bathroom Industry

The kitchen and bathroom industry as a more labor-intensive industry, the automation of the production process is necessary. Welding with Han's Robot can be deployed flexibly and easily, and it can solve the problem of recruitment difficulties for manual labor, thus reducing costs and increasing efficiency

